

Universidad Nacional de Colombia (UNAL) Sede Manizales

Undergraduate Program in Information Systems SILABO

CS251. Computer graphics (Elective)

2022-II

1. General information	General information		
1.1 School	:	Sistemas de Información	
1.2 Course	:	CS251. Computer graphics	
1.3 Semester	:	7^{mo} Semestre.	
1.4 Prerrequisites	:		
		\bullet MA307. Mathematics applied to computing . (6 th Sem)	
1.5 Type of course	:	Elective	
1.6 Learning modality	:	Face to face	
1.7 Horas	:	2 HT; 2 HP; 2 HL;	
1.8 Credits	:	4	

2. Professors

3. Course foundation

It offers an introduction to the area of Computer Graphics, which is an important part of Computer Science. The purpose of this course is to investigate the fundamental principles, techniques and tools for this area.

4. Summary

1. Fundamental Concepts 2. Basic Rendering 3. Programming Interactive Systems 4. Geometric Modeling 5. Advanced Rendering 6. Computer Animation

5. Generales Goals

- Bring students to concepts and techniques used in complex 3-D graphics applications.
- Give the student the necessary tools to determine which graphics software and which platform are best suited to develop a specific application.

6. Contribution to Outcomes

This discipline contributes to the achievement of the following outcomes:

- 1) Analyze a complex computing problem and to apply principles of computing and other relevant disciplines to identify solutions. (Usage)
- 6) Apply computer science theory and software development fundamentals to produce computing-based solutions. (Usage)

7. Content

UNIT 1: Fundamental Concepts (6)					
Competences:					
Content	Generales Goals				
 Media applications including user interfaces, audio and video editing, game engines, cad, visualization, virtual reality Tradeoffs between storing data and re-computing data as embodied by vector and raster representations of images Additive and subtractive color models (CMYK and RGB) and why these provide a range of colors Animation as a sequence of still images 	 Explain in general terms how analog signals can be reasonably represented by discrete samples, for example, how images can be represented by pixels [Familiarity] Describe color models and their use in graphics display devices [Familiarity] Describe the tradeoffs between storing information vs storing enough information to reproduce the information, as in the difference between vector and raster rendering [Familiarity] Describe the basic process of producing continuous motion from a sequence of discrete frames (sometimes called "flicker fusion") [Familiarity] 				
Readings: Hearn and Baker (1990)					

UNIT 2: Basic Rendering (12)				
Competences: Content Generales Goals				
Content	Generales Goals			
 Rendering in nature, e.g., the emission and scattering of light and its relation to numerical integration Forward and backward rendering (i.e., ray-casting and rasterization) 	• Discuss the light transport problem and its relation to numerical integration ie, light is emitted, scatters around the scene, and is measured by the eye [Familiarity]			
Basic radiometry, similar triangles, and projection model	Describe the basic graphics pipeline and how forward and backward rendering factor in this [Familiarity]			
• Affine and coordinate system transformations	• Create a program to display 3D models of simple graphics images [Usage]			
• Ray tracing	 Obtain 2-dimensional and 3-dimensional points by applying affine transformations [Usage] Apply 3-dimensional coordinate system and the changes required to extend 2D transformation operations to handle transformations in 3D [Usage] 			
\bullet Visibility and occlusion, including solutions to this				
problem such as depth buffering, Painter's algorithm, and ray tracing				
• Simple triangle rasterization				
• Rendering with a shader-based API	• Contrast forward and backward rendering [Assessment]			
\bullet Application of spatial data structures to rendering	• Explain the concept and applications of texture map ping, sampling, and anti-aliasing [Familiarity]			
• Sampling and anti-aliasing				
• Forward and backward rendering (i.e., ray-casting and rasterization)	• Explain the ray tracing/rasterization duality for the visibility problem [Familiarity]			
	• Implement a simple real-time renderer using a raster- ization API (eg, OpenGL) using vertex buffers and shaders [Usage]			
	• Compute space requirements based on resolution and color coding [Assessment]			
	• Compute time requirements based on refresh rates rasterization techniques [Assessment]			
Readings: Hearn and Baker (1990), Hughes et al. (2013), Wolff (2011), Shreiner et al. (2013)				

UNIT 3: Programming Interactive Systems (2)					
Competences:					
Content	Generales Goals				
 Event management and user interaction Approaches to design, implementation and evaluation of non-mouse interaction Touch and multi-touch interfaces Shared, embodied, and large interfaces New input modalities (such as sensor and location data) New Windows, e.g., iPhone, Android Speech recognition and natural language processing Wearable and tangible interfaces Persuasive interaction and emotion Ubiquitous and context-aware interaction technologies (Ubicomp) Bayesian inference (e.g. predictive text, guided pointing) Ambient/peripheral display and interaction 	Discuss the advantages (and disadvantages) of non-mouse interfaces [Assessment]				
D 1' H 1D 1 (1000)					
Readings: Hearn and Baker (1990)					

UNIT 4: Geometric Modeling (15) Competences: Content Generales Goals • Basic geometric operations such as intersection cal-• Represent curves and surfaces using both implicit culation and proximity tests and parametric forms [Usage] • Volumes, voxels, and point-based representations • Create simple polyhedral models by surface tessellation [Usage] • Parametric polynomial curves and surfaces • Generate a mesh representation from an implicit sur-• Implicit representation of curves and surfaces face [Usage] • Approximation techniques such as polynomial • Generate a mesh from data points acquired with a curves, Bezier curves, spline curves and surfaces, and laser scanner [Usage] nonuniform rational basis (NURB) spines, and level set method • Construct CSG models from simple primitives, such as cubes and quadric surfaces [Usage] • Surface representation techniques including tessellation, mesh representation, mesh fairing, and mesh • Contrast modeling approaches with respect to space generation techniques such as Delaunay triangulaand time complexity and quality of image [Assesstion, marching cubes ment] Spatial subdivision techniques • Procedural models such as fractals, generative modeling, and L-systems • Elastically deformable and freeform deformable models • Subdivision surfaces • Multiresolution modeling • Reconstruction • Constructive Solid Geometry (CSG) representation Readings: Hearn and Baker (1990), Shreiner et al. (2013) IINIT 5: Advanced Rendering (6)

UNIT 5: Advanced Rendering (6)					
Competences:					
Content	Generales Goals				
 Time (motion blur), lens position (focus), and continuous frequency (color) and their impact on rendering Shadow mapping Occlusion culling Subsurface scattering Non-photorealistic rendering GPU architecture 	 Demonstrate how an algorithm estimates a solution to the rendering equation [Assessment] Prove the properties of a rendering algorithm, eg, complete, consistent, and unbiased [Assessment] Implement a non-trivial shading algorithm (eg, toon shading, cascaded shadow maps) under a rasterization API [Usage] Discuss how a particular artistic technique might be implemented in a renderer [Familiarity] 				
• Human visual systems including adaptation to light, sensitivity to noise, and flicker fusion	• Explain how to recognize the graphics techniques used to create a particular image [Familiarity]				

Readings: Hearn and Baker (1990), Hughes et al. (2013), Wolff (2011), Shreiner et al. (2013)

UNIT 6: Computer Animation (4) Competences: Content Generales Goals • Forward and inverse kinematics • Compute the location and orientation of model parts using an forward kinematic approach [Usage] • Collision detection and response • Implement the spline interpolation method for pro- Procedural animation noise, rules ducing in-between positions and orientations [Usage] (boids/crowds), and particle systems • Implement algorithms for physical modeling of parti-• Skinning algorithms cle dynamics using simple Newtonian mechanics, for example Witkin & Kass, snakes and worms, symplec-• Physics based motions including rigid body dynamtic Euler, Stormer/Verlet, or midpoint Euler methics, physical particle systems, mass-spring networks ods [Usage] for cloth and flesh and hair • Discuss the basic ideas behind some methods for • Key-frame animation fluid dynamics for modeling ballistic trajectories, for • Splines example for splashes, dust, fire, or smoke [Familiarity • Data structures for rotations, such as quaternions • Use common animation software to construct simple • Camera animation organic forms using metaball and skeleton [Usage] • Motion capture Readings: Hearn and Baker (1990), Shreiner et al. (2013)

8. Methodology

El profesor del curso presentará clases teóricas de los temas señalados en el programa propiciando la intervención de los alumnos.

El profesor del curso presentará demostraciones para fundamentar clases teóricas.

El profesor y los alumnos realizarán prácticas

Los alumnos deberán asistir a clase habiendo leído lo que el profesor va a presentar. De esta manera se facilitará la comprensión y los estudiantes estarán en mejores condiciones de hacer consultas en clase.

9. Assessment

Continuous Assessment 1 : 20 %

Partial Exam : 30 %

Continuous Assessment 2 : 20 %

Final exam : 30 %

References

Hearn, Donald and Pauline Baker (1990). Computer Graphics in C. Prentice Hall. Hughes, John F. et al. (2013). Computer Graphics - Principles and Practice 3rd Edition. Addison-Wesley. Shreiner, Dave et al. (2013). OpenGL, Programming Guide, Eighth Edition. Addison-Wesley. Wolff, David (2011). OpenGL 4.0 Shading Language Cookbook. Packt Publishing.